Lassi Michael

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PhD student in Biorobotics at the Computational Neuroengineering Lab. Fascinated by data analysis, machine learning and neuroscientific research. With a problem-solver attitude, I am comfortable working in a team and in challenging environments. I am always trying to learn from others and to give my original contribution.

Work Experience and Projects

Machine learning algorithms for the prediction of neurological disorders

Pisa, IT

PhD Degree, Sant'Anna School of Advanced Studies

October 2020 - In progress

- Developing algorithms for the prognosis of rehabilitation outcome after stroke and for the onset prediction of Alzheimer's disease by merging multi-modal (neural, genetic, clinical) data.
- Working closely with clinical partners and performing data collection on stroke subjects.

Analysis and prediction of motor responses elicited by TMS

Genève, CH

Master Project, UPHUMMEL Laboratory, EPFL Supervisor: Prof. Hummel Friedhelm September 2019 - February 2020

- Evaluation of predictability of multi-muscle motor responses to TMS through the use of machine learning models.
- Evaluation of the possible presence of synergistic responses in motor evoked potentials after TMS stimulation.
- Developed small GUI in Matlab for synergies extraction of multiple muscle responses elicited by TMS
- Acquired experimental knowledge in EMG signal acquisition and transcranial magnetic stimulation.

Computer vision for 3D hands pose reconstruction

Lausanne, CH

Internship, Logitech Europe SA

February 2019 - August 2019

- Use of deep learning algorithms to estimate position of hands' keypoints in RGB images.
- Combination of classical computer vision models and neural networks to achieve real-time pose estimation without loss of accuracy.
- Software development in C++ to process video stream.

Sensorimotor control of fine grasping in primates

Fribourg, CH

Semester project, TNE Laboratory, EPFL

September 2018 - January 2019

Supervisor: Prof. Micera Silvestro

- Processing of kinematic macaque's upper limb data, as well as neural data from motor cortex.
- Exploration of a dataset of local field potentials, in order to extract significant and consistent features of grasping behavior.
- Use of supervised machine learning tools in order to decode different kind of grasping behaviors from monkey's cortical activity.

Natural control of a BCI-driven robot

Lausanne, CH

Course Project, CNBI - Center for non-invasive brain interfaces Prof. Millán José del R. February 2018 - June 2018

- Teamwork-based project to develop a classifier able to distinguish left and right hand motor-imagery tasks from cortical electroencephalographic data.
- Performance assessment in real-time application of various supervised machine learning algorithms.
- Basic experience in the use of 16 channel EEG recording systems.

Humanoid robot control for rehabilitation

Milano, IT

Bachelor's Thesis, NEARLab - Neuroengineering and Medical Robotics Lab March 2017–July 2017 Supervisor: Prof. Pedrocchi Alessandra

- Development of C++ software for the integration of Inertial Measurement Units and humanoid NAO Robot, via movement mirroring.
- Programmed basic robot interactions with the user.
- Postprocessing analysis and evaluation of subjects' task execution based on Matlab scripts.

Education

École Polytechnique Federale de Lausanne (EPFL)

Lausanne, CH

Master's degree, Bioengineering (Neuroprosthetics), **GPA:** 5.68/6 September 2017 – February 2020 Data Analysis, Neuroscience, Machine Learning, Brain-Computer Interaction Locomotion Analysis, Signal Processing, Neuroengineering

Award: Excellence Fellowship

Politecnico di Milano Milano, IT

Biomechanics, Biomaterials, **Grade: 110/110 cum laude**October 2014 – July 2017

PRINCIPLES OF ELECTRONICS, COMPUTER SCIENCE

Award: Premio Migliori Matricole 2014 (Best Freshman Award)

Liceo Scientifico A. Einstein

Rimini, IT

Secondary Diploma, Grade: 100/100 cum laude

September 2009-July 2014

Award: Albo Nazionale delle Eccellenze 2013 (National Board of Excellence)

Technical and Personal skills

o Programming Languages:

- Python
- Matlab
- **-** C++
- C

o Languages:

- Italian: Native
- English: C1 (IELTS Certificate 2017: 8.0/9.0),
- French: Basic skills

o Industrial Software:

- MS Office
- LATEX
- Visual Studio
- Comsol Multiphysics
- Vicon Nexus

o General Skills:

- Good oral presentation skills
- Teamwork attitude
- Keeping rational in front of problems
- Eager to learn new skills